

Using a neural network on "Coders Strike Back"

because why not

By bleuj

16 June 2016

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What we try to achieve here

A light decent runner..

- ▶ Supervised learning on a good runner bot using a neural network.

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What we try to achieve here

A light decent runner..

- ▶ Supervised learning on a good runner bot using a neural network.
- ▶ Constrained memory use of the neural network.

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What we try to achieve here

A light decent runner..

- ▶ Supervised learning on a good runner bot using a neural network.
- ▶ Constrained memory use of the neural network.
- ▶ Low time cost with the neural network bot (to make all of this slightly less useless).

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Machine learning problem

- ▶ Given a data set of inputs and associated outputs, machine learning and statistics techniques can help to generalize a data set.

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Machine learning problem

- ▶ Given a data set of inputs and associated outputs, machine learning and statistics techniques can help to generalize a data set.
- ▶ Here we will try to imitate a bot.

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Machine learning problem

- ▶ Given a data set of inputs and associated outputs, machine learning and statistics techniques can help to generalize a data set.
- ▶ Here we will try to imitate a bot.
- ▶ We must choose inputs and outputs to imitate a reference bot.

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Machine learning problem

- ▶ Given a data set of inputs and associated outputs, machine learning and statistics techniques can help to generalize a data set.
- ▶ Here we will try to imitate a bot.
- ▶ We must choose inputs and outputs to imitate a reference bot.
- ▶ Then the neural network will be a function to generalize the data gathered about the reference bot.

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Machine learning problem

- ▶ Given a data set of inputs and associated outputs, machine learning and statistics techniques can help to generalize a data set.
- ▶ Here we will try to imitate a bot.
- ▶ We must choose inputs and outputs to imitate a reference bot.
- ▶ Then the neural network will be a function to generalize the data gathered about the reference bot.
- ▶ Neural networks are one of many methods to do that.

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- ▶ 1 - Coding a good normal bot.

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- ▶ 2 - Using a simulator to generate data to learn.

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- ▶ 3 - Learning the data on a neural network.

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- ▶ 2 - Using a simulator to generate data to learn.
- ▶ 3 - Learning the data on a neural network.
- ▶ 4 - Importing the neural network on CodinGame.

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Reference bot

- ▶ Bot that minimizes the distance to run, with a depth of 8.

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Reference bot

- ▶ Bot that minimizes the distance to run, with a depth of 8.
- ▶ Minimization done with simulated annealing heuristic.

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Reference bot

- ▶ Bot that minimizes the distance to run, with a depth of 8.
- ▶ Minimization done with simulated annealing heuristic.
- ▶ Extra points for reaching checkpoints early, for having some speed, and good angles at the end.

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Reference bot

- ▶ Bot that minimizes the distance to run, with a depth of 8.
- ▶ Minimization done with simulated annealing heuristic.
- ▶ Extra points for reaching checkpoints early, for having some speed, and good angles at the end.
- ▶ Does not care about the opponent.

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Simulating things and creating data outside of CodinGame

- ▶ Visualization to verify your bot seems correct outside of CodinGame (I use Qt).

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Simulating things and creating data outside of CodinGame

- ▶ Visualization to verify your bot seems correct outside of CodinGame (I use Qt).
- ▶ Lots of simulations are run with random checkpoint positions, random speed and angles (speed and pod angles), picked out data from there.

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Simulating things and creating data outside of CodinGame

- ▶ Visualization to verify your bot seems correct outside of CodinGame (I use Qt).
- ▶ Lots of simulations are run with random checkpoint positions, random speed and angles (speed and pod angles), picked out data from there.
- ▶ Data saved with C++ ofstream.

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About inputs and outputs

- ▶ The inputs should be invariant by translation and rotation, because it doesn't restrict you, and otherwise there's useless extra difficulty to learn.

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About inputs and outputs

- ▶ The inputs should be invariant by translation and rotation, because it doesn't restrict you, and otherwise there's useless extra difficulty to learn.
- ▶ The inputs must take into account at least the 2 next checkpoints.

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About inputs and outputs

- ▶ The inputs should be invariant by translation and rotation, because it doesn't restrict you, and otherwise there's useless extra difficulty to learn.
- ▶ The inputs must take into account at least the 2 next checkpoints.
- ▶ Outputs are simply : chosen angle difference, and thrust choice.

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About inputs and outputs

- ▶ The inputs should be invariant by translation and rotation, because it doesn't restrict you, and otherwise there's useless extra difficulty to learn.
- ▶ The inputs must take into account at least the 2 next checkpoints.
- ▶ Outputs are simply : chosen angle difference, and thrust choice.
- ▶ Normalizing everything (for example between 0 and 1) helps a lot the learning part of the Neural network.

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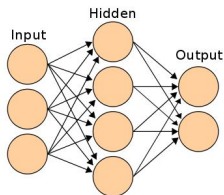
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Neural network architecture

- ▶ The function defined by a neural network is easy to understand with a picture.



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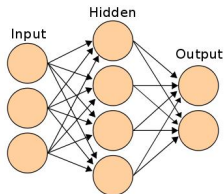
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Neural network architecture

- ▶ The function defined by a neural network is easy to understand with a picture.
- ▶ Values go from inputs to outputs as follows : when you are on an arrow you are multiplied by a weight, on a neuron the value is the sum of the values that arrive. When you leave a hidden neuron, you apply a non linear function (for example tanh).



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- ▶ I only use one hidden layer.

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- ▶ I only use one hidden layer.
- ▶ I use bias (neurons always equal to one).

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Neural network architecture

- ▶ I only use one hidden layer.
- ▶ I use bias (neurons always equal to one).
- ▶ The hidden layer is a rectified linear unit (ReLU) layer (Found its implementation on stack overflow).

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Neural network architecture

- ▶ I only use one hidden layer.
- ▶ I use bias (neurons always equal to one).
- ▶ The hidden layer is a rectified linear unit (ReLU) layer (Found its implementation on stack overflow).
- ▶ Data saved with C++ ofstream.

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- ▶ A neural network function relies on a lot of parameters (weights), and you have to optimize them so that it best fits a data set.

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Learning a neural network function

- ▶ A neural network function relies on a lot of parameters (weights), and you have to optimize them so that it best fits a data set.
- ▶ It's quite tricky to optimize (back-propagation, stochastic gradient descent...), especially if you don't want to change all your code if you add a layer or something like that.

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- ▶ A neural network function relies on a lot of parameters (weights), and you have to optimize them so that it best fits a data set.
- ▶ It's quite tricky to optimize (back-propagation, stochastic gradient descent...), especially if you don't want to change all your code if you add a layer or something like that.
- ▶ There are lots of libraries to do that.

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Learning a neural network function

- ▶ A neural network function relies on a lot of parameters (weights), and you have to optimize them so that it best fits a data set.
- ▶ It's quite tricky to optimize (back-propagation, stochastic gradient descent...), especially if you don't want to change all your code if you add a layer or something like that.
- ▶ There are lots of libraries to do that.
- ▶ I use PyBrain on Python (first one that worked for me).

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- ▶ A neural network function relies on a lot of parameters (weights), and you have to optimize them so that it best fits a data set.
- ▶ It's quite tricky to optimize (back-propagation, stochastic gradient descent...), especially if you don't want to change all your code if you add a layer or something like that.
- ▶ There are lots of libraries to do that.
- ▶ I use PyBrain on Python (first one that worked for me).
- ▶ It's very simple to use after reading the short tutorial on its website, but quite slow.

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- ▶ A neural network function relies on a lot of parameters (weights), and you have to optimize them so that it best fits a data set.
- ▶ It's quite tricky to optimize (back-propagation, stochastic gradient descent...), especially if you don't want to change all your code if you add a layer or something like that.
- ▶ There are lots of libraries to do that.
- ▶ I use PyBrain on Python (first one that worked for me).
- ▶ It's very simple to use after reading the short tutorial on its website, but quite slow.
- ▶ Data produced with C++ code is opened with `file = open('mydata.txt', 'r')` and `file.readline()`.

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- ▶ There are lots of libraries to do that.
- ▶ I use PyBrain on Python (first one that worked for me).
- ▶ It's very simple to use after reading the short tutorial on its website, but quite slow.
- ▶ Data produced with C++ code is opened with `file = open('mydata.txt', 'r')` and `file.readline()`.
- ▶ Saving the weights was a little tricky with PyBrain (a post on stack-overflow helped me).

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- ▶ The functions to create the inputs of the data set are used again here.

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- ▶ The functions to create the inputs of the data set are used again here.
- ▶ Weights arrays are read from 4 very ugly 1-dimensional arrays that are created by the python code, and that are just copy-pasted every time.

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- ▶ New arrays are something more understandable.

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- ▶ The functions to create the inputs of the data set are used again here.
- ▶ Weights arrays are read from 4 very ugly 1-dimensional arrays that are created by the python code, and that are just copy-pasted every time.
- ▶ New arrays are something more understandable.
- ▶ Carefully implemented neural network on CodinGame using the definition/architecture of the neural network.

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- ▶ Now we have a bot ready to compete with others

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- ▶ Now we have a bot ready to compete with others
- ▶ The bot may fail to cross many checkpoints, so it can be a good idea to reduce checkpoint radius in simulation.

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- ▶ Now we have a bot ready to compete with others
- ▶ The bot may fail to cross many checkpoints, so it can be a good idea to reduce checkpoint radius in simulation.
- ▶ Another trick is to exaggerate thrust and angle difference given by the neural network.

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