

# AP PHYSICS C MECHANICS: FORMULA SHEET VI baguetteroni

## NUMBERS

### Trigonometric Functions

$\theta$	$0^\circ$	$30^\circ$	$37^\circ$	$45^\circ$	$53^\circ$	$60^\circ$	$90^\circ$
$\sin \theta$	0	$1/2$	$3/5$	$\sqrt{2}/2$	$4/5$	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	$4/5$	$\sqrt{2}/2$	$3/5$	$1/2$	0
$\tan \theta$	0	$\sqrt{3}/3$	$3/4$	1	$4/3$	$\sqrt{3}$	$\infty$

### Unit Symbols

m - meter  
kg - kilogram  
s - second  
C - coulomb  
N - newton  
J - joule

### Prefixes

Factor	Prefix	Symbol
$10^9$	Giga	G
$10^6$	mega	M
$10^3$	kilo	k
$10^{-2}$	centi	c
$10^{-3}$	milli	m
$10^{-6}$	micro	$\mu$
$10^{-9}$	nano	n
$10^{-12}$	pico	p

### Important constants

Speed of light  $c = 3.00 \cdot 10^8 \text{ m/s}$   
 universal grav. constant  $G = 6.67 \cdot 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2}$   
 acceleration  $g = 9.8 \text{ m/s}^2$

### Important assumption

#1 Frame of reference of any problem is inertial unless otherwise stated

## Geometry Trigonometry

Rectangle  $A = bh$   
 Triangle  $A = \frac{1}{2}bh$   
 Circle  $A = \pi r^2$   
 $C = 2\pi r$   
 $s = r\phi$   
 $v = eWh$

rectangular solid  $V = eWh$

cylinder  $V = \pi r^2 e$   
 $S = 2\pi r e + 2\pi r^2$

sphere  $V = \frac{4}{3}\pi r^3$   
 $S = 4\pi r^2$

Right Triangle  $a^2 + b^2 = c^2$

## FORMULA

### KINEMATIC

$$v = \frac{dx}{dt} \quad \Delta x = \int_{t_0}^{t_f} v(t) dt$$

$$a = \frac{dv}{dt} \quad \Delta v = \int_{t_0}^{t_f} a(t) dt$$

} BASIC FORMULAS FOR acceleration

### BIGS Kinematic Equations

$$v = v_0 + at$$

$$\Delta x = \left( \frac{v + v_0}{2} \right) t$$

$$\Delta x = v_0 t + \frac{1}{2} at^2$$

$$\Delta x = vt - \frac{1}{2} at^2$$

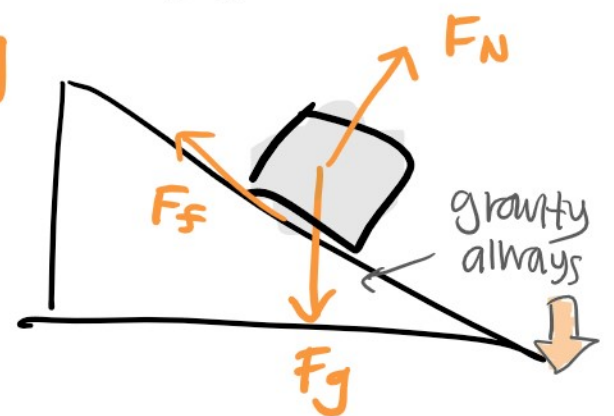
$$v^2 = v_0^2 + 2a\Delta x$$

} acceleration MUST be constant

### Newton's Law

Newton's 2nd Law

$$\sum F = ma$$



Friction formula

$$F_f = \mu F_N$$

← Always perpendicular to surface

Tension - solve using  $\sum F = ma$ ; Tension always constant along string

### COLLISION

$$F = \frac{dp}{dt}$$

$$\Delta P_i = \Delta P_f$$

} CONSERVATION OF LINEAR MOMENTUM

IMPULSE  $F\Delta t = J = \Delta P = \Delta MV$

$$J = \int_{t_1}^{t_2} F(t) dt$$

} CALCULUS IMPULSE

### Center of mass

$$x_{cm} = \frac{1}{M} \int x dm = \frac{1}{M} \int x (\lambda dx)$$

$$\lambda = \frac{dm}{dx}$$

↑ linear density

$$M = \int dm = \int \lambda dx$$

↑ Find the mass

### Work energy power

$$\Delta E = W = \int F dx$$

} energy

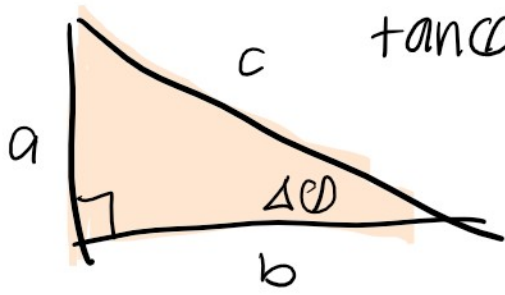
RIGHT Triangle

$$a^2 + b^2 = c^2$$

$$\sin \theta = a/c$$

$$\cos \theta = b/c$$

$$\tan \theta = a/b$$



$$\Delta E = W = \int F \cdot dx \quad \text{energy work}$$

$$P = \frac{dE}{dt} = \frac{W}{t} = Fv \quad \text{power}$$

$$PE_{\text{grav}} = mgh \quad PE_{\text{spring}} = \frac{1}{2}kx^2$$

$$KE = \frac{1}{2}mv^2$$

## ROTATIONAL MOTION

$$\Delta x = r \Delta \theta$$

$$v = r \omega$$

$$a = r \alpha$$

LINEAR &  
ANGULAR

$$W = \int_{\theta_1}^{\theta_2} \tau d\theta$$

$$P = \tau \omega \quad \text{POWER FORMULA}$$

$$\tau = \vec{r} \times \vec{F} = I \alpha \quad \text{Torque}$$

$$I = \int r^2 dm \quad \text{ROTATIONAL INERTIA}$$

$$KE = \frac{1}{2} I \omega^2 \quad \text{ANGULAR KE}$$

$$L = I \omega = r p \quad \text{angular momentum}$$

## CENTRIPETAL ACCELERATION

$$L_i = L_f \quad \text{CONSERVATION OF ANGULAR momentum}$$

$$a_c = \frac{v^2}{r} = r \omega^2$$