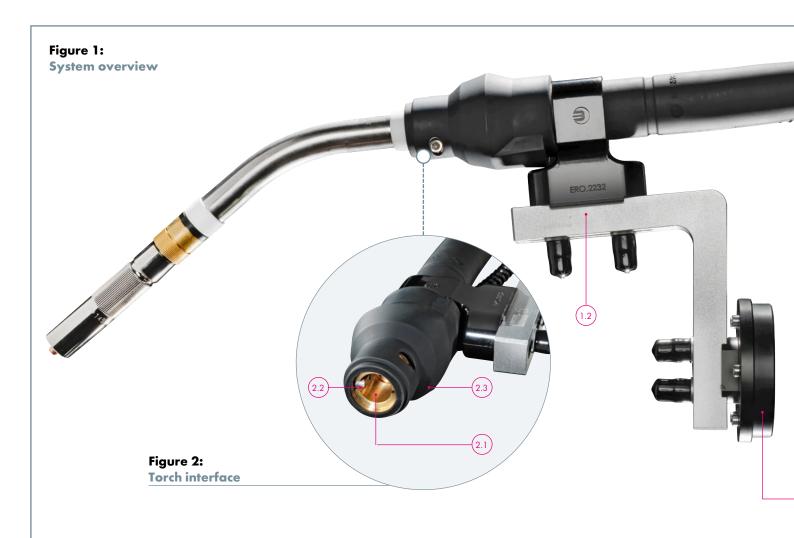


CAT Compact

System overview and technical data



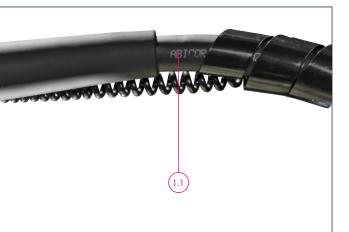
Reduced to the max: Compact, precise, simple, fast installation and value formoney The robot mount CAT Compact with fast installation cable assembly for air-cooled welding applications was designed for use on over arm robots up to 500 A. The overall system includes a welding torch, collision sensor and cable assembly with a heavy-duty and torsion-resistant coaxial cable for long service life.

The torch neck versions ABIROB® G 350, G 360 and G 500, which are equipped with the G-interface, are available to complement the CAT Compact system. Their outstanding features include stability and repeat accuracy — for good and reproducible welding results.

The torch neck types of the G-series are available in various TCP versions and can fall back on the tried-and-trusted wearing part concept of the ABIROB® A and ABIROB® GC-series.

Arguments that speak for themselves:

- Excellent purchasing price, combined with a fast and simple installation and long service life
- Compact design size for better access in tight and complex jigs or components
- Good reset-precision combined with large deflection for good reproducible welding results and the optimum protection of robot and welding torch
- Extensive range of welding torches
- Two cable assembly types available for standard applications with rubber cable support and for heavy dynamic welding application with spring support
- Technically sophisticated, robust design
- Excellent protection against contamination
- Worldwide Product support available



1.3

Figure 1: System overview

- 1.1 Changeable cable assembly to the CAT Compact, for an simple-and fast installation
- 1.2 Bracket
- 1.3 Robot flange

Figure 2:

Torch interface

- 2.1 Changeable torch interface
- 2.2 Key-way for precise positioning of the welding torch
- 2.3 HNBR rubber protection against welding spatter and soiling

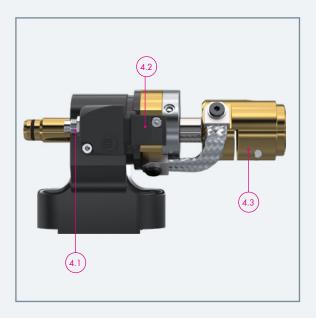
Figure 3: Shock Sensor

Modular shock sensor, simple and fast installation Quick connection for signal cable



Figure 4: CAT Compact

- 4.1 Signal/emergency stop4.2 Switch housing
- 4.3 Interface/torch interface G-series



CAT Compact

Technical data



Technical data (EN 60 974-7):

ABIROB® G 350

Rating: 350 A CO₂ 300 A M21

Duty cycle: 100%

Wire: 0.8 - 1.4 mm

Neck geometries: 30°/35°/45°

ABIROB® G 360

Rating: 360 A CO₂

290 A M21

Duty cycle: 100%

Wire: 0.8 - 1.6 mm

Neck geometries: $22^{\circ}/35^{\circ}/45^{\circ}$

ABIROB® G 500

Rating: 500 A CO₂ 400 A M21

DA CO₂

Duty cycle: 100 %

Wire: 0.8 - 1.6 mm Neck geometries: 22°/35°/45°

Technical data:

CAT Compact

Dimensions: 148 x 69 x 88 mm

Weight: approx.0.85 kg

approx. 1.3 kg (incl. bracket and flange)

Electrical data: switching capacity 24 VDC / 100 mA

Switching point: - deflection in X, Y direction approx. 2.5°

- deflection in Z axis approx. 0.8 mm

X-, Y-direction approx. 9.5°

Z-direction approx. 3 mm

Release accuracy: all directions $\leq \pm 0.3$ mm

(L = 300 mm)

Max. release distance:

(L = 300 mm)

Protection class:

Relative humidity:

Ambient Temperature: during operation -10°C to +55°C

storage and transportation -10°C to +55°C

during operation up to 70% at 20 °C

storage and transportation up to 70% at 20°C

CAT Compact

Order information and technical details

Torch neck

Torch type	22 °	30°	35°	45°
	Part-No.	Part-No.	Part-No.	Part-No.
ABIROB®G350	-	980.0190.1	980.0185.1	980.0203.1
ABIROB®G360	980.0215.1	-	980.0222.1	980.0216.1
ABIROB®G 500	980.0208.1	-	980.0223.1	980.0209.1

CAT Compact



Description	Part-No.
Robot mount CAT Compact	780.2137.1
shock sensor for all torch types	
including protective cover	

Cable assemblies



CAT Compact cable assemblies inc	luding	shock sensor
Description	Length	Part-No.
Spring cable support, Panasonic®connector	1.1m	980.0274.1
Spring cable support, Euro connector	1.1 m	980.0275.1
Rubber cable support,Panasonic®connector	1.1 m	980.0272.1
Rubber cable support, Euro connector	1.1 m	980.0273.1

Liners



Description	Part-No.
Liner 2.1x5.5x2000 for Euro connector	124.0145.1
Liner 2.1x5.5x3600 for Panasonic®connector	124.0190.1

Adaptor Flanges



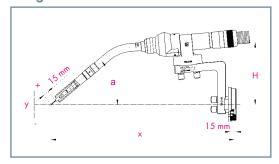
Type of robot	Part-No.
ABB 1410/1600; OTC NV 6/NV 6L; Kuka KR5 ARC	780.0604.1
PANASONIC TM1400	780.1604.1
KAWASAKI RA06L	780.0698.1
MOTOMAN MA 1440/MA 2010	780.0682.1
FANUC 100iC/M-10iA/M-20iA	780.0682.1

Holder



Description	Part-No.
L Bracket for CAT Compact, adjustable	780.2135.1
L Bracket for CAT Compact, not adjustable	780.2133.1

TCP geometries



Torch Type	TCP data				
Description	x(mm)	Y(mm)	H(mm)	α	Part-No.
G35030°	419.5	36.8	1 <i>57</i>	35°	980.0190.1
G35035°	461.3	0	1 <i>57</i>	40°	980.0185.1
G350 45°	434.4	-26.9	1 <i>57</i>	50°	980.0203.1
G360 22°	442.8	<i>77</i> .1	1 <i>57</i>	27°	980.0215.1
G360 45°	406.7	23.4	1 <i>57</i>	50°	980.0216.1
G500 22°	442.8	<i>77</i> .1	1 <i>57</i>	27°	980.0208.1
G500 45°	406.7	23.4	157	50°	980.0209.1





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