The 道(Tao) of Parallelism in Algorithms

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Exploiting parallelism in irregular algorithms

Parallel programming needs new abstractions

- dependence graphs are inadequate: cannot represent parallelism in irregular algorithms

New abstraction:

- operator formulation
- data centric abstraction

(regular algorithms become special case)

Key insights

- amorphous data parallelism (ADP) is ubiquitous
- TAO analysis: structure in algorithms
 - use TAO structure to exploit ADP efficiently

Inadequacy of static dependence graphs

Node: computations

Ege: dependeces between computations

> computations that are not ordered by the transitive closure of the dependence relation can be executed in parallel.

> dependences between computations in irregular algorithms are functions of runtime data values, so they cannot be rep- resented usefully by a static dependence graph.

Inadequacy of static dependence graphs - Example

Delaunay mesh refinement

- Don't care non-determinism
- final mesh depends on order in
- which bad triangles are processed

Data structure: graph

- nodes: triangles
- edges: triangle adjacencies

Parallelism

- triangles with disjoint cavities can be processed in parallel
- parallelism depends on runtime values
- static dependence graph cannot be generated
- parallelization must be done at runtime



Figure 1. Fixing bad triangles

example: Delaunay Mesh Refinement (DMR)

Operator formulation of algorithms

> algorithm is viewed in terms of its action(operator) on data structure

- active elements
- neighbourhoods: nodes that might be read/written
- ordering
- > Amorphous data parallelism (ADP)
- process active nodes in parallel, subject to neighborhood and ordering constraints
 - how do we exploit ADP



Figure 4. Active elements and neighborhoods

Tao-analysis of algorithms



Figure 6. Structural analysis of algorithms

Amorphous data-parallelism - Implementation Strategy

- Baseline: speculative parallel execution
- Exploiting structure to reduce overheads: is it a <u>cautious</u> algorithm
- Exploiting structure for coordinated scheduling
 - autonomous (baseline implementation)
 - uncoordinated: online conflict detection, rollback for correct execution
 - coordinated (eliminating speculative overheads)
 - coordinated: only non-conflicting iterations are scheduled for parallel execution



Figure 9. Scheduling strategies

Case studies of algorithms: tao-analysis + implementation strategy

- Operator: Morph
 - refinement
 - coarsening
 - edge contraction
 - node elimination
 - sub-graph contraction
 - general morph
- Operator: Local computation
 - topology-driven
 - o data-driven
- Operator: Reader

Case studies of applications

Barnes-Hut n-body simulation: four phases, each with a different structural classification

- 1. Tree-build:
 - a. topology: tree
 - b. operator: refinement morph
 - c. active nodes: topology-driven and unordered
- 2. Summarize:
 - a. topology: tree
 - b. operator: local computation
 - c. active nodes: topology-driven and ordered
- 3. Force-computation:
 - a. topology: tree
 - b. operator: reader
 - c. active nodes: unordered
- 4. Force update:
 - a. topology: set
 - b. operator: local computation
 - c. active nodes: topology-driven and unordered



(b) Speedup for 1,000,000 bodies; sequential runtime is 122.2 s.

Extensions

- 1. Nested amorphous data-parallelism a.
- 2. Pipeline parallelism

a.

- 3. Task parallel execution
 - a.

Conclusion

- to do