

MECHANICAL ENGINEERING PAPER-I

1. Engineering Mechanics:

Analysis of force systems, friction, centroid and centre of gravity, trusses and beams, principle of virtual work, kinematics and kinetics of particle, kinematics and kinetics of rigid bodies.

2. Mechanism and Machines:

Velocity and acceleration of links, cams and followers gears and gear trains clutches, belt drives, brakes and dynamometers, Flywheel and governors, balancing of rotating and reciprocating masses, balancing of multi cylinder engines, Free and forced vibration, damped vibration, whirling of shafts.

3. Mechanics of Solids:

Stresses and strains, compound stresses strains, Torsion of circular shafts, stresses and deflections in beams unsymmetrical bending, curved beams, Thin and thick cylinders and spheres, Buckling of columns, Energy methods, helical and leaf springs.

4. Design of Machine Elements:

Design for Static and dynamic loading, Theories of failure, fatigue principles of design of rivetted, welded and bolted joints, shafts, springs, bearings, brakes, clutches and flywheels.

5. Engineering Materials:

Crystal systems and crystallography, crystal imperfections, Alloys and phase diagrams, Heat treatment, ferrous and non ferrous metals and alloys, Mechanical properties and testing.

6. Manufacturing:

Metal casting, metal forming, metal joining, Mechanics of metal cutting, machining and machine tool operations, unconventional machining methods limits, fits and tolerances, inspection: Surface roughness, comparators, computer integrated manufacturing, Flexible manufacturing systems, jigs and fixtures

7. Industrial Engineering:

Production, planning and control, inventory control and operation, research, CPM and PERT.

8. Mechatronics and Robotics:

Microprocessors and microcontrollers, Architecture, Programming, Computer interfacing Programmable logic controller, sensors and actuators, Piezoelectric accelerometers, Hall effect sensors, optical encoder, resolver, Inductosyn, Pneumatic and Hydraulic Actuators, stepper motor, control system, mathematical modeling, control signals, controllability and observability, Robotics: Robot classification, robot specification. Notation: Direct and inverse kinematics homogeneous co-ordinates and arm equation of four axis SCARA Robot.

MECHANICAL ENGINEERING

PAPER-II

1. Thermodynamics:

Thermodynamic systems and processes, properties of pure substances, concepts and applications of zeroth, first and second law of thermodynamics, entropy, availability and irreversibility, detailed analysis of thermodynamic cycles, ideal and real gases, fuels and combustion.

2. Fluid Mechanics:

Basic concepts and properties of fluids, manometry, fluid statics, buoyancy, equations of motion, Bernoulli's equation and applications, viscous flow of incompressible fluids, laminar and turbulent flows, flow through pipes and head losses in pipes, dimensional analysis, Forces on immersed bodies and boundary layer over a flat plate, isentropic and adiabatic flows, normal shock waves.

3. Heat Transfer:

Modes of heat transfer, steady and unsteady heat conduction, thermocouple time constant, critical thickness of insulation, heat transfer from fins, momentum and energy equations for boundary layer flow on a flat plate. Free and forced convection, radiation heat transfer, Stefan-Boltzmann law, shape factor, black and grey body radiation heat exchange, boiling and condensation, heat exchanger analysis, LMTD and NTU – effectiveness methods.

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